

SUVAT

S: Displacement (m)

U: Initial Velocity (ms^{-1})

V: Final Velocity (ms^{-1})

A: Acceleration (ms^{-2})

T: Time (s)

$$v = u + at$$

$$v^2 = u^2 + 2as$$

$$s = ut + \frac{1}{2}at^2$$

$$s = vt - \frac{1}{2}at^2$$

$$s = \frac{1}{2}(u + v)t$$

Under gravity $a = g (-9.8ms^{-1})$

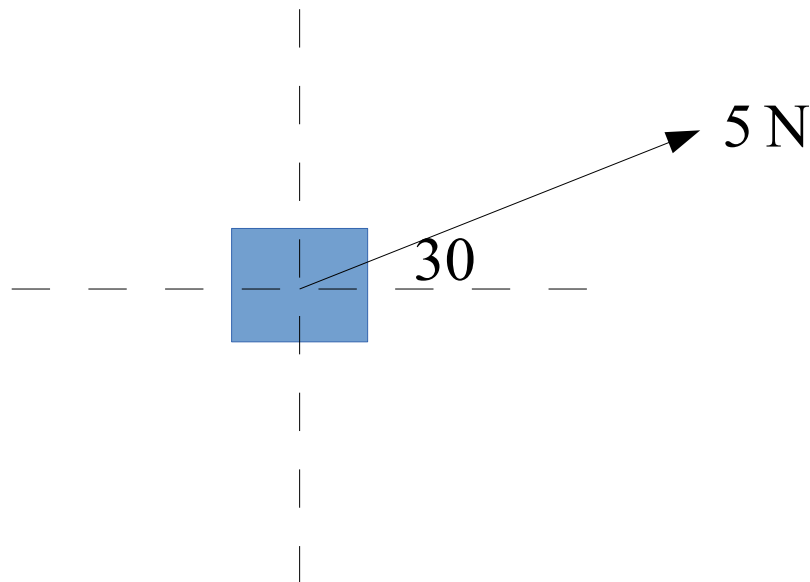
On a speed time graph:
Area is distance travelled
Gradient is acceleration

Dynamics

$$F = ma$$

The resultant force is equal to mass times acceleration

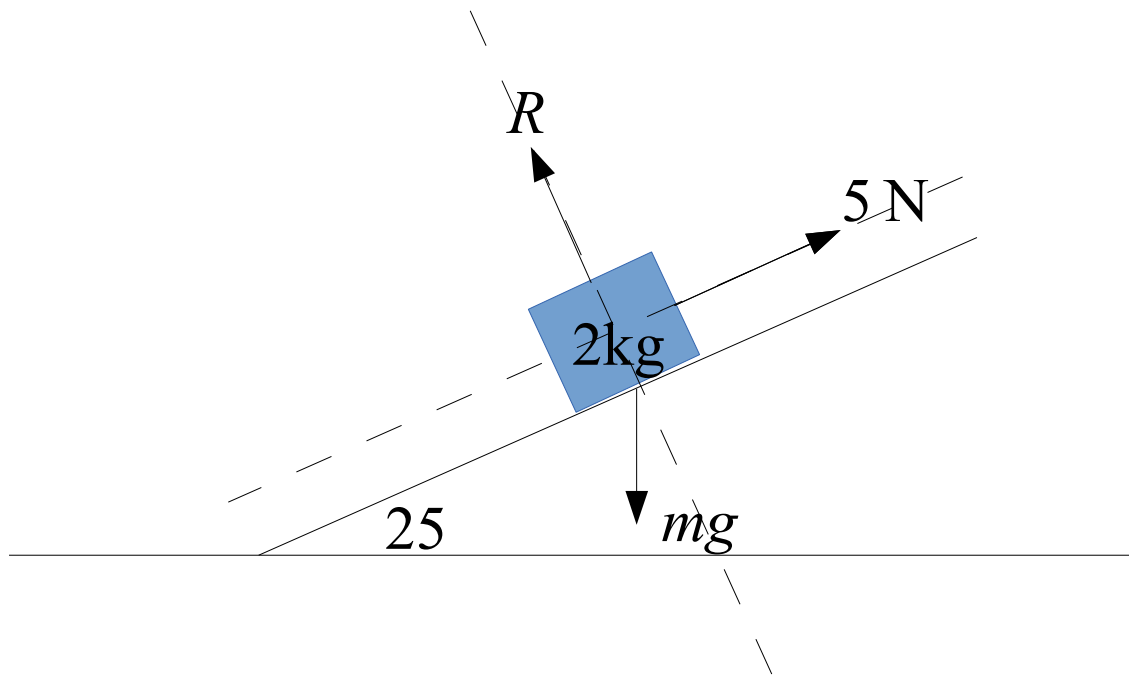
We often need to split a force into horizontal and vertical components:



Force acting horizontally = $5 \cos(30)$

Force acting vertically = $5 \sin(30)$

Dynamics



Perpendicular to the Plane:

$$R = 2g \cos(25)$$
$$R = 17.76 \text{ N (2dp)}$$

Parallel to the Plane:

$$F = ma$$
$$2g \sin(25) - 5 = 2a$$
$$a = 1.64 \text{ ms}^{-1} \text{ (2dp)}$$

$$Friction_{MAX} = \mu R$$

μ is the coefficient of friction

$$0 < \mu < 1$$

Dynamics

Momentum

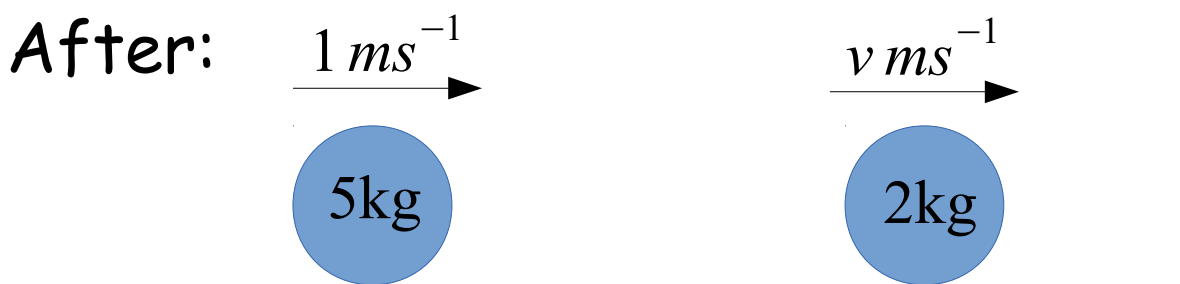
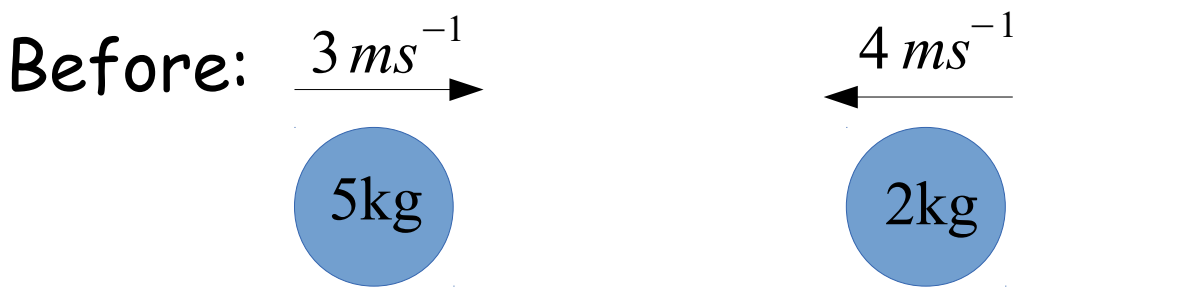
$$\text{Momentum} = mv$$

Impulse = change in momentum

$$I = mv - mu$$

Conservation of Momentum

$$m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$$



$$m_1 u_1 + m_2 u_2 = m_1 v_1 + m_2 v_2$$

$$5(3) + 2(-4) = 5(1) + 2(v)$$

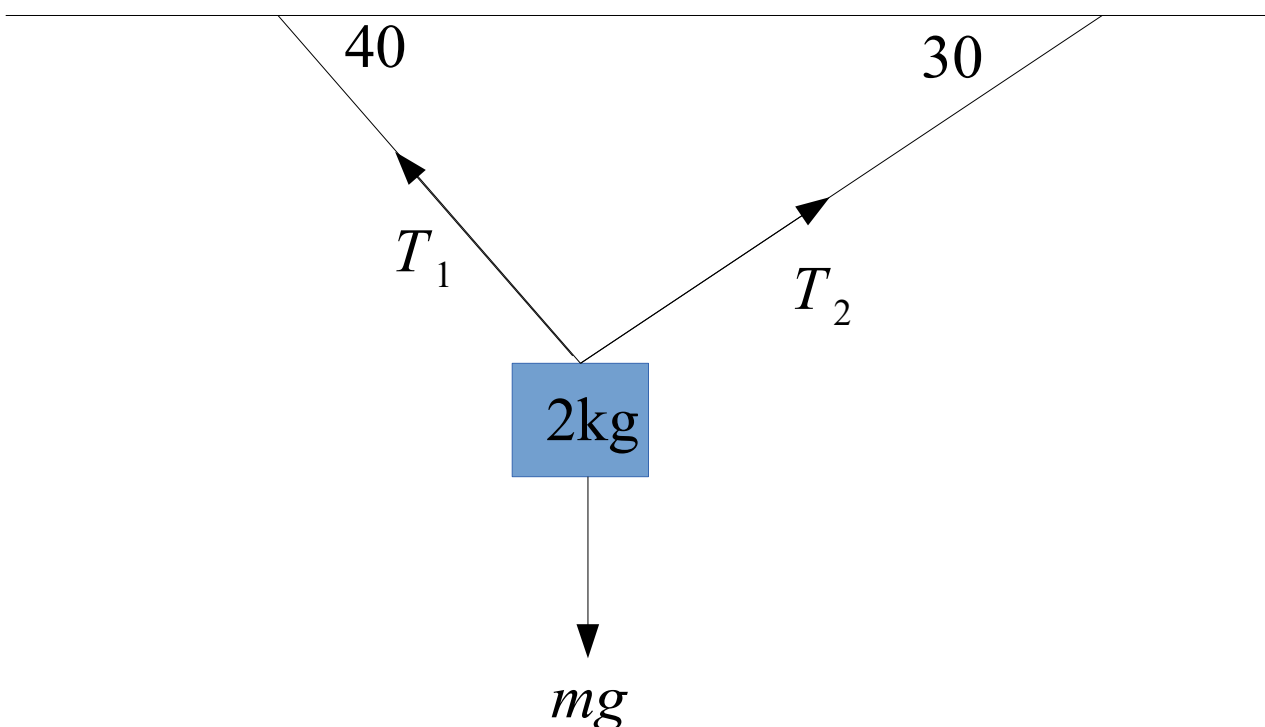
$$2 = 2(v)$$

$$v = 1 \text{ ms}^{-1}$$

Statics

If an object is in equilibrium all forces in all directions must be equal

Forces up = Forces down
Forces Left = Forces right



Forces left = Forces right
 $T_1 \cos(40) = T_2 \cos(30)$

Forces up = Forces down
 $T_1 \sin(40) + T_2 \sin(30) = 2g$

(We can find T_1 and T_2 by solving the simultaneous equations)

Moments

$$\text{Moment} = F \times d$$

A moment is a turning force

d is the distance from the pivot

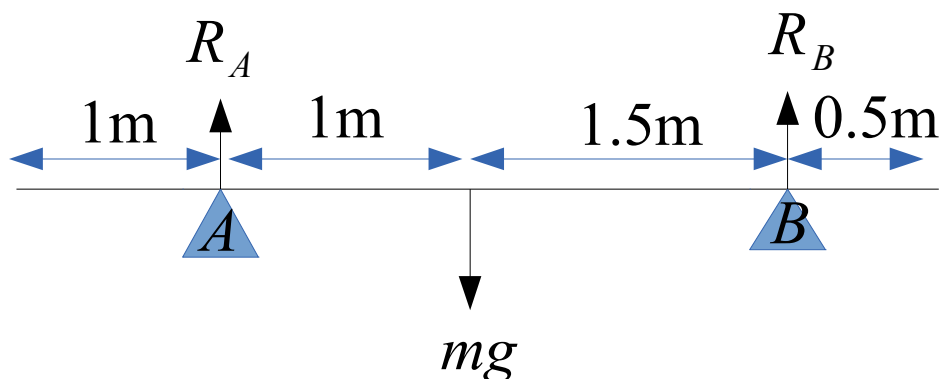
If a plank is uniform the weight acts from the centre

In equilibrium

Clockwise Moments = Anticlockwise Moments

Forces up = Forces down

In Equilibrium: uniform plank of mass 10kg



Taking moments about A

$$1 \times 10g = 2.5 \times R_B$$

$$R_B = 4g$$

Forces up = Forces down

$$R_A + R_B = 10g$$

$$R_A = 6g$$

Vectors

Vectors have a magnitude and direction

The i direction is along the positive x axis,
 j direction is along the positive y axis

$$R = R_0 + vt$$

The position of a vector is the starting
point + velocity times time

We use Pythagoras to find:

The length of a line

The magnitude of a force

The speed

the direction of \vec{AB} is the position of B
minus the position of A